Bioinformatics Software Lab Introduction to Analysis of Single Cell Sequencing

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Objectives

- 1. basics of single cell sequencing
- 2. basic bioinformatics/computational problems
 - dimension reduction
 - clustering
 - data integration

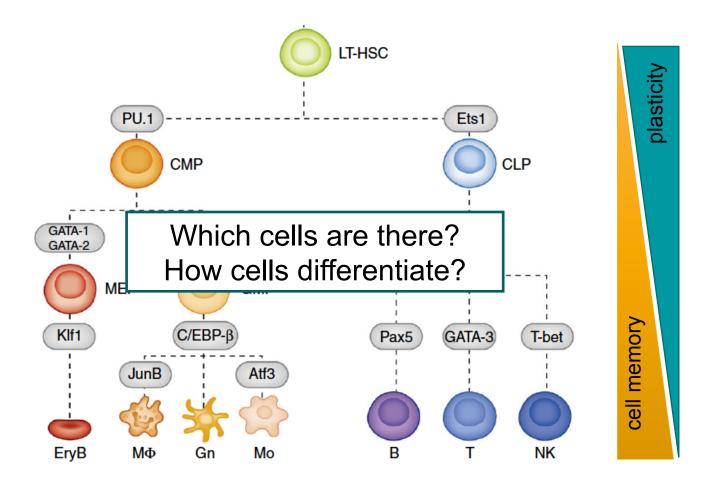


Expression at Single Cell Level

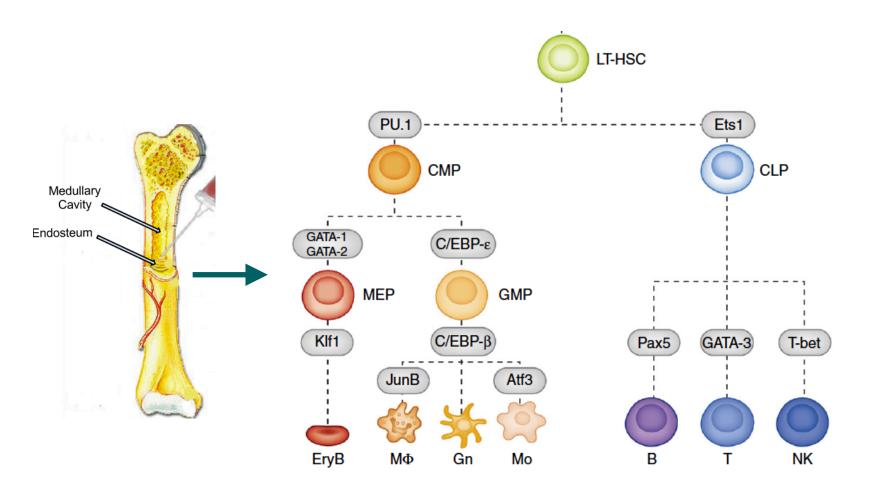


Cell Differentiation

Hematopoiesis

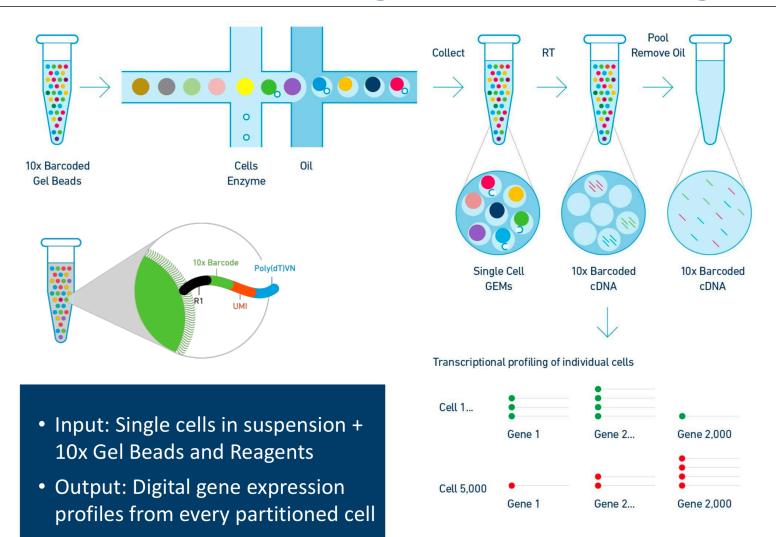


Cell Differentiation



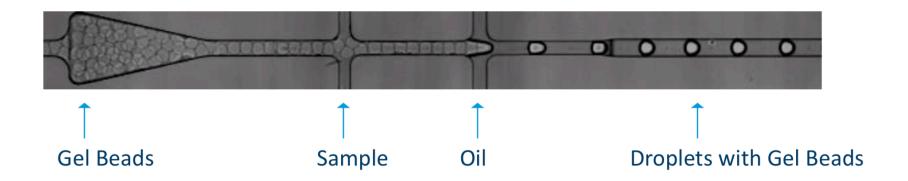
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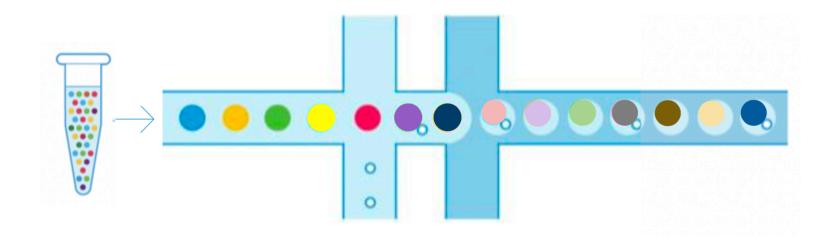
Droplet based RNA single cell sequencing



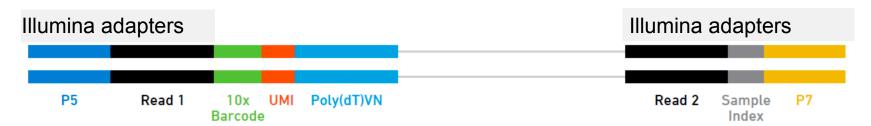


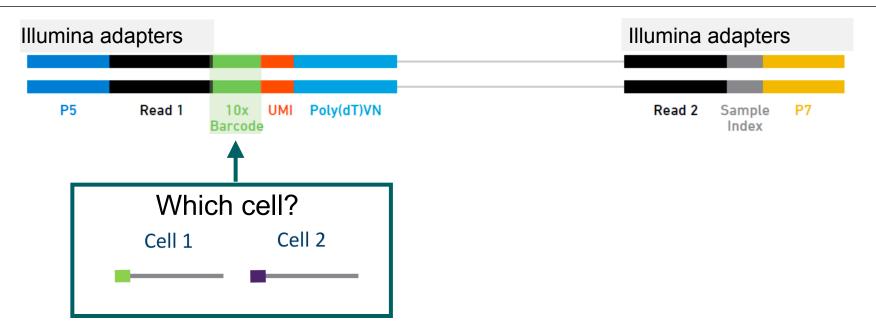
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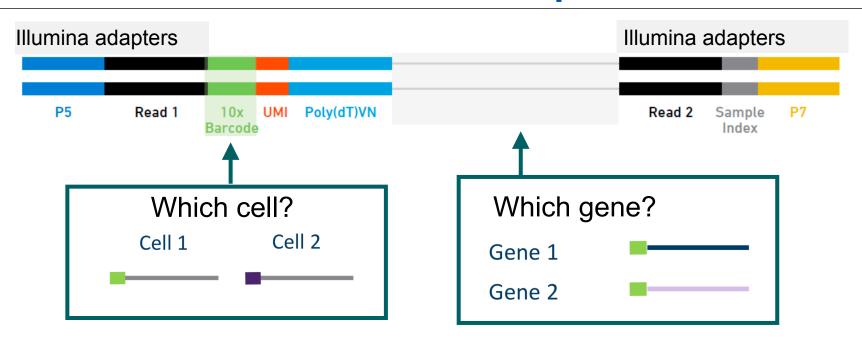


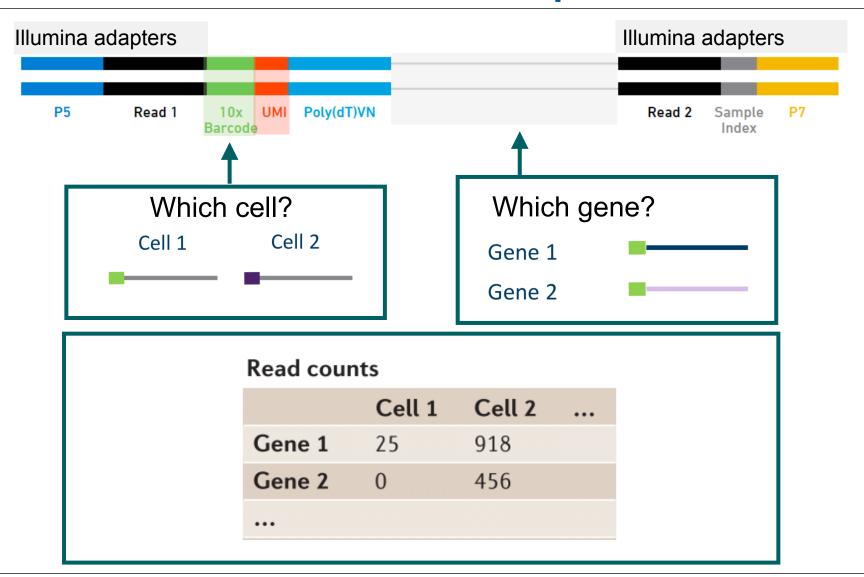






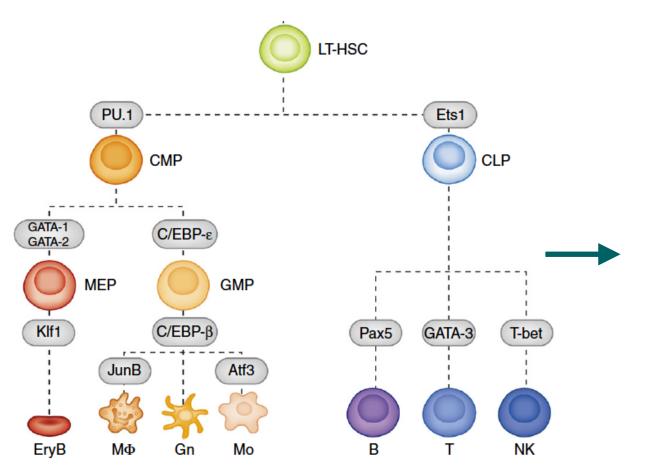








Cell Differentiation & Gene Expression

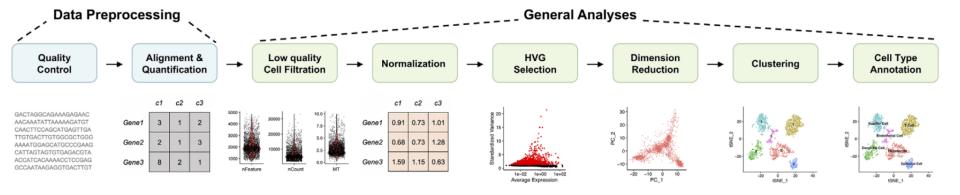


	Cell 1	Cell 2	
Gene 1	25	918	
Gene 2	0	456	
Gene 3	20	342	
Gene 4	0	214	

Source: Amit (2016), Nature Immunoloy.

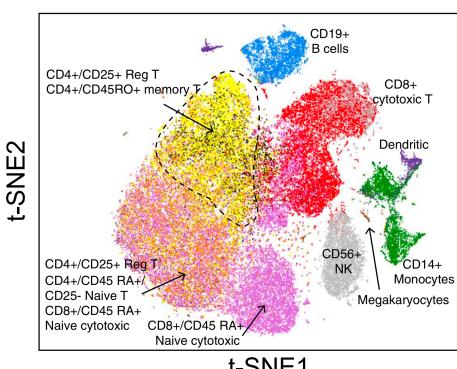


Basics Bioinformatics - single cell RNA-seq



Gene Expression of Lymphoid Cells

PBMCs from Humans

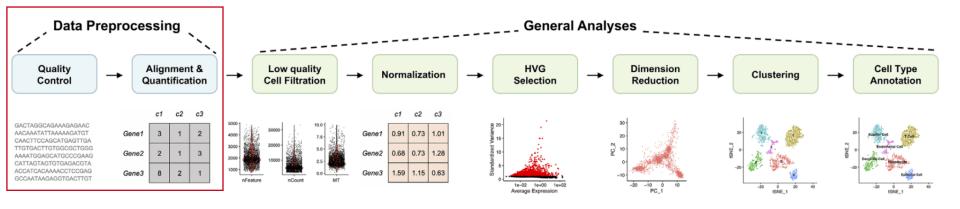


t-SNE1

Single cell RNA-seq from 68k cells

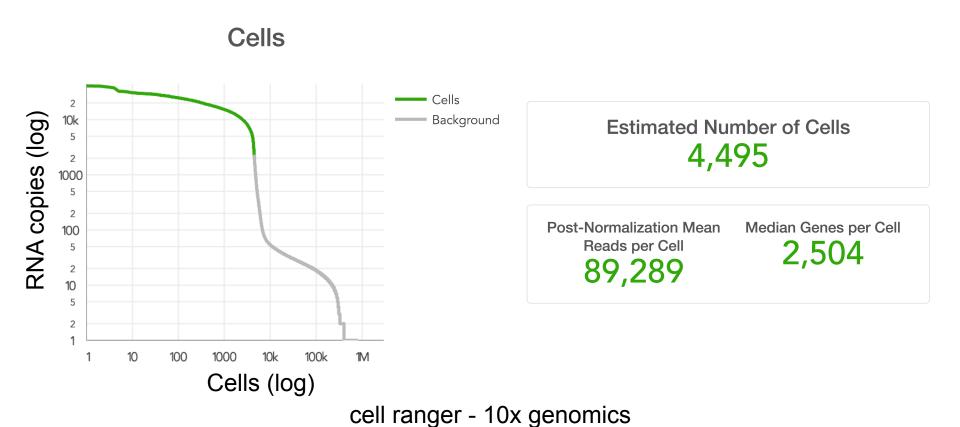
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Basics Bioinformatics - single cell RNA-seq



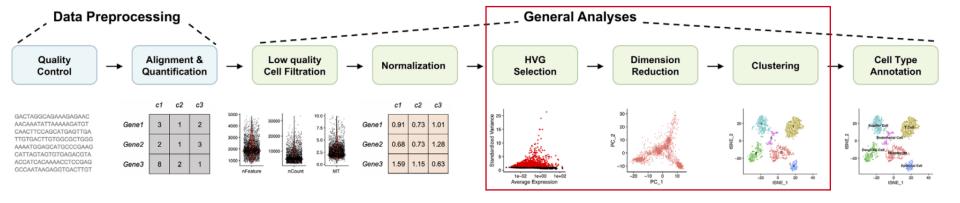
Basics Bioinformatics - Cell Filtering

- 1. sum UMIs (copy of transcripts) per cell
- 2. consider cells with total UMI count > 99th of expected recovered cells





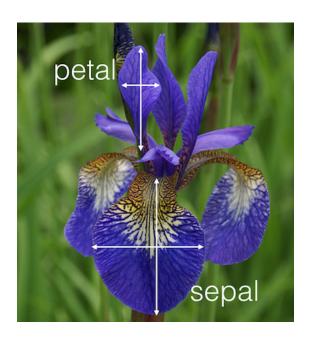
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Clustering & Dimension reduction



- Given a data description
 - i.e. measurement of size of iris flowers
- Find groups of similar observations
 - i.e. iris flower sub-types

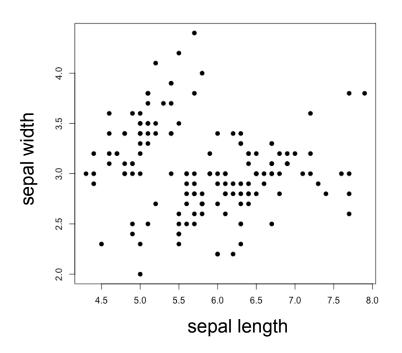


	Sepal Length	Sepal Width	Petal Length	Petal Width
Flower 1	5.1	3.5	1.4	0.2
Flower 2	4.9	3.0	1.4	0.2
Flower 3	4.7	3.2	1.3	0.2
Flower 4	4.6	3.1	1.5	0.2



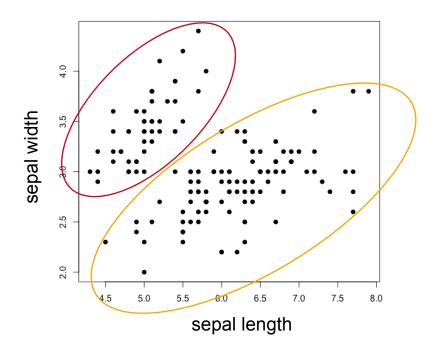
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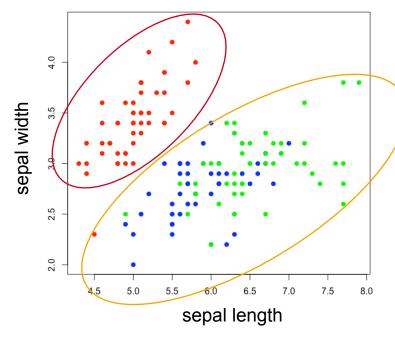
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Iris Setosa





Iris Virginia



Iris Versicolor



Clustering Formalism

For a given data:

 Matrix X with N observations and L dimensions where x_i is a vector representing observation i

X11	X12	 X1L
X21	X22	 X 2L
X 31	X 32	 X 3L
X _{N1}	X _{N2}	 XNL

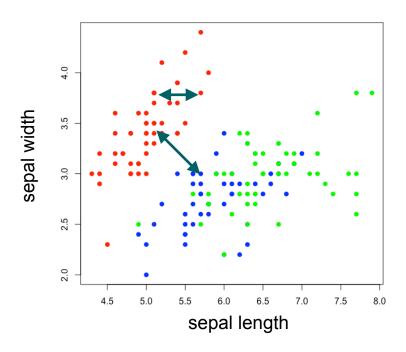
find groups of similar observations

• vector $Y = (y_1, ..., y_N)$ where $y_i \in \{1, ..., K\}$ indicates the cluster of observation i



Distance

- A important concept in clustering is a distance (similarity)
 between a pair of objects x_i and x_j
 - Observations of a same group should be close in space

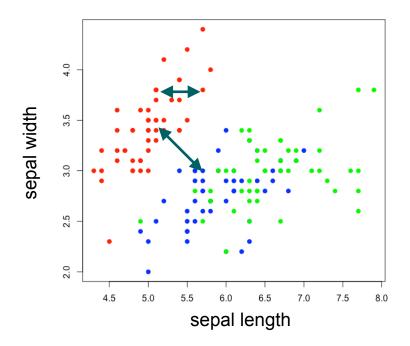


Euclidean distance (sensitive to scale)

$$d(x_i, x_j) = \sqrt{\sum_{l=1}^{L} (x_{il} - x_{jl})^2}$$

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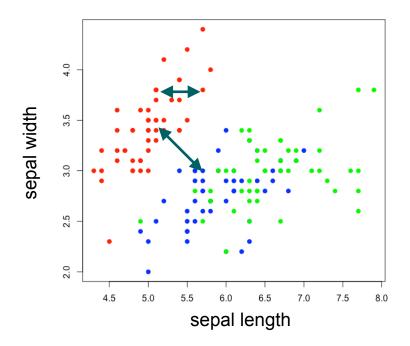
Pearson Correlation (scale insensitive/ similarity)

$$d(x_i, x_j) = \frac{\sum_{l=1}^{L} (x_{il} - \overline{x}_i)(x_{jl} - \overline{x}_j)}{\sigma_i^2 \sigma_j^2}$$



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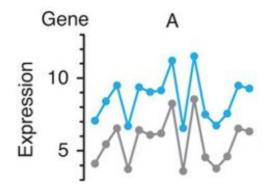
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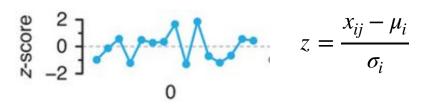
Distance and Scale

- In some problems scale can be important!
 - Similarly in changes are more important / not absolute values.

unscaled data



Euclidean - not similar Correlation - similar z-score normalised data



Euclidean - similar Correlation - similar



Clustering Methods

Hierarchical methods

- Mostly bottom up
- based on distance / simple to interpret
- Partitional methods (k-means or mixture models)
 - Mostly top down
 - Use models of groups, centroids
- Graph based methods
 - Use graph formalisms to represent data:
 - nodes are objects
 - edges weights represent similarities
 - find well connected graphs



K-means

Iterative algorithm using **centroids** as cluster representations

Requires specification of number of clusters (K)

Algorithm:

Start cluster (Y) randomly

Repeat for a number of iterations

- estimate centroid (m_k) for each cluster

$$m_k = \frac{\sum_{i=1}^{N} 1(y_i = k) x_i}{\sum_{i=1}^{N} 1(y_i = k)}$$

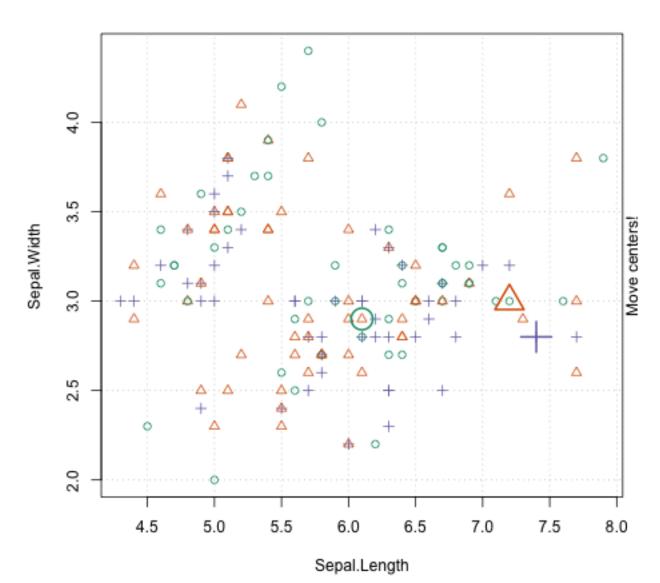
Assign objects to closest centroid:

$$y_i = \operatorname{argmin}_k \operatorname{d}(x_i, m_k)$$

^{*} convergence is only guaranteed for Euclidean distance

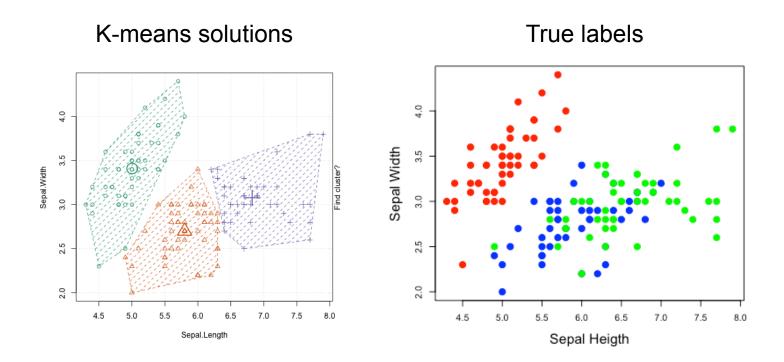


K-means on Iris





K-means on Iris

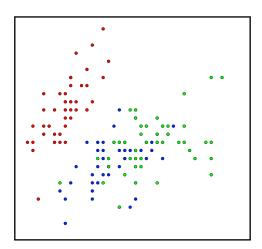


- K-means tends to find spherical clusters
- Sensitive to initialisation

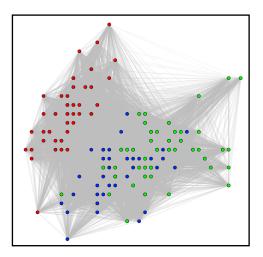


• data points are nodes



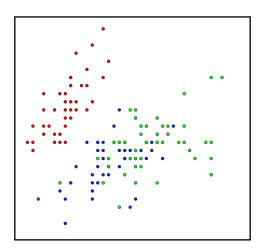


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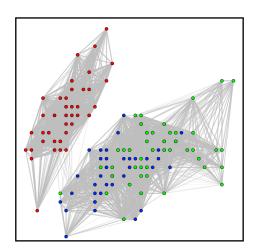


• edges represent similarities

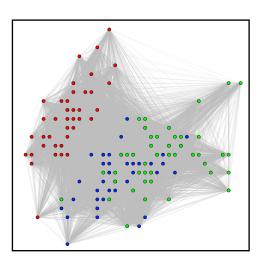




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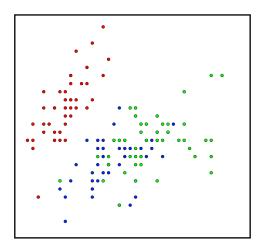


 k-nearest neighbours (KNN) -> sparse graphs

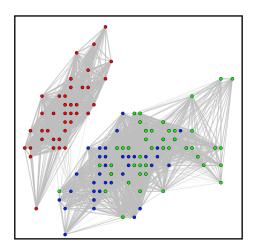


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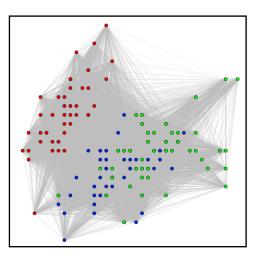




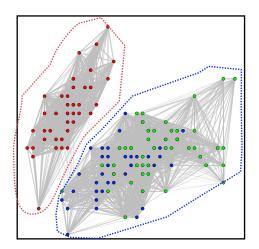
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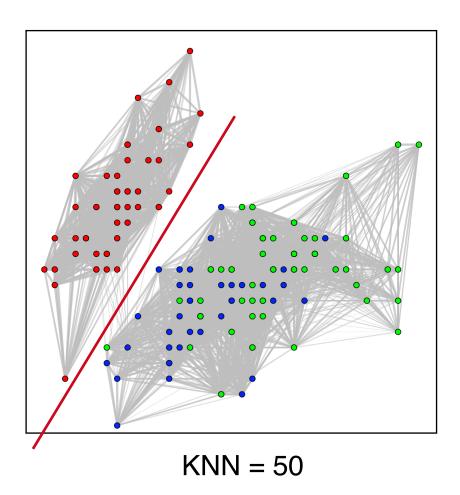
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• find well connected sub-graphs

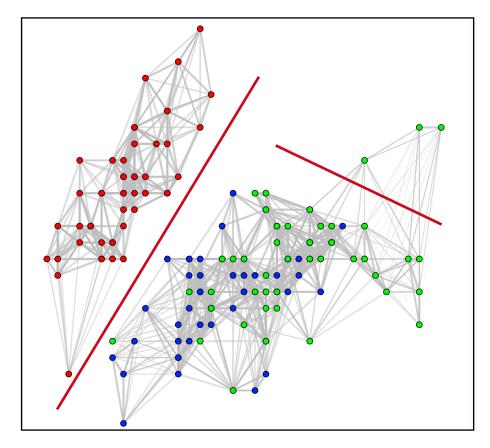


Graph cut



- Cluster by finding cuts in the graph
- Cut cost C(A,B) = sum of edge weights in cut

Graph cut

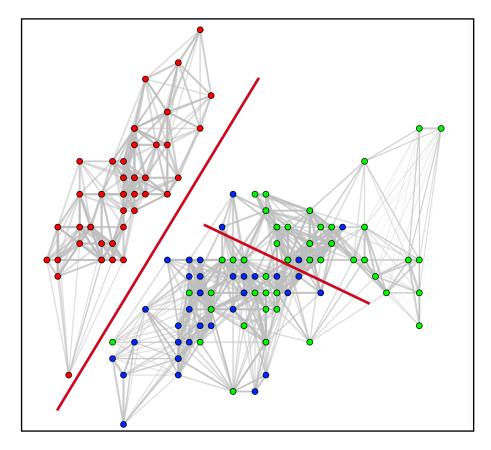


KNN = 10

- Cluster by finding cuts in the graph
- Cut cost C(A,B) = sum of edge weights in cut
 - smallest cuts might not be the best



Normalized graph cut



KNN = 10

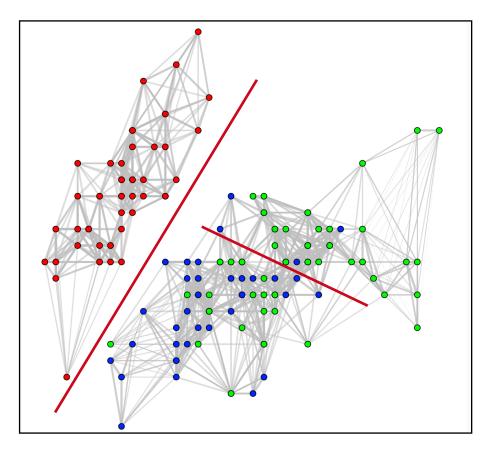
 Normalized graph cut avoids small graphs

$$normCUT(A,B) = \frac{CUT(A,B)}{VOL(A)} + \frac{CUT(A,B)}{VOL(B)}$$

where VOL(A) is the weight sums of cluster A.



Spectral Clustering



KNN = 10

- Let A be an adjacent matrix of the graph:
 - a_{ij}=1 if nodes i and j are connected
- A laplacian matrix is defined as:

$$L = D - A$$

- where D is a diagonal matrix with the number of neighbours of a node
- If we perform a spectral analysis of L*

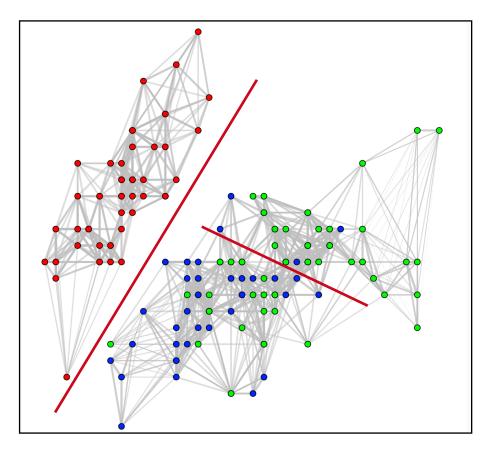
$$L\lambda = u\lambda$$

- eigenvectors (λ) provides CUTs in the graph
- eigenvalues (*u*) provides the cost of the CUT.
- Perform k-means on lowest K eigenvalues

^{*} see for more details: http://www.tml.cs.uni-tuebingen.de/team/luxburg/publications/Luxburg07_tutorial.pdf



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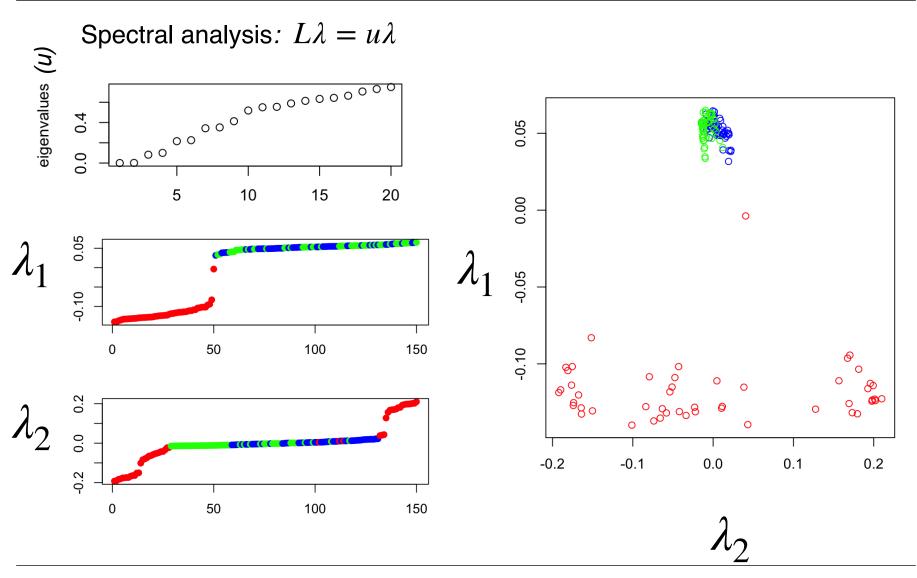
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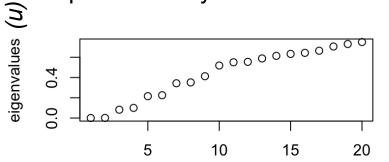
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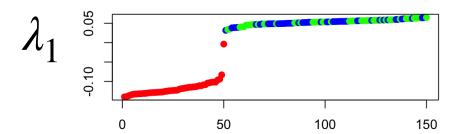
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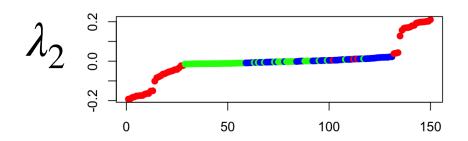


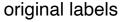


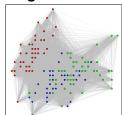


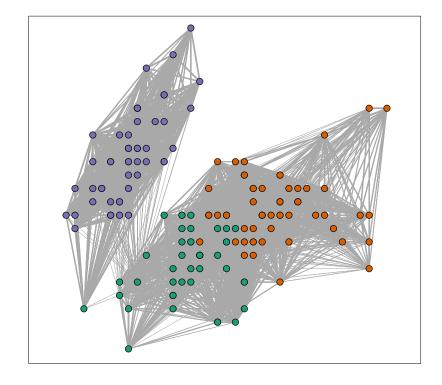




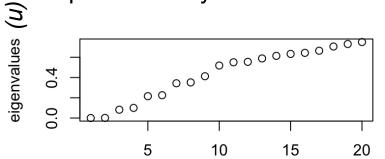


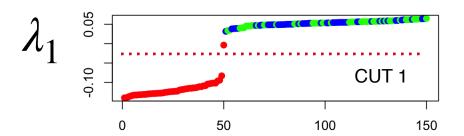


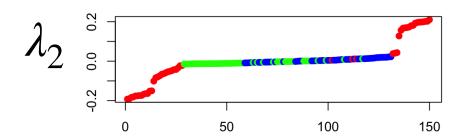


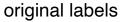


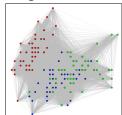


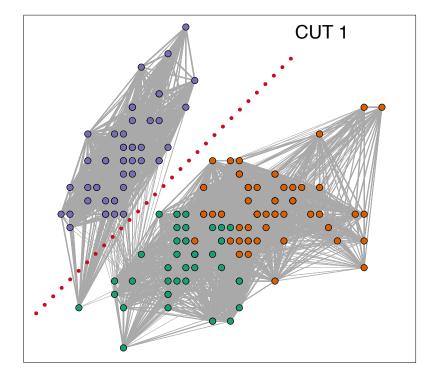




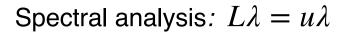


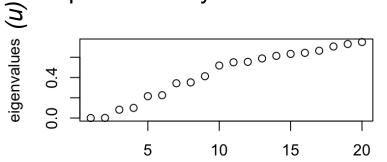


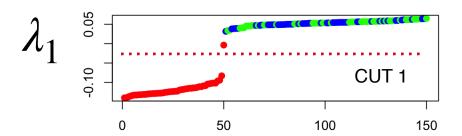


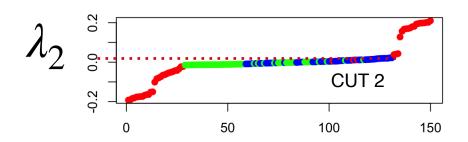


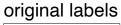


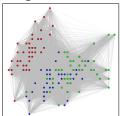


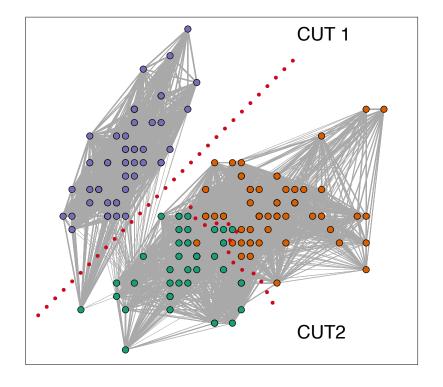


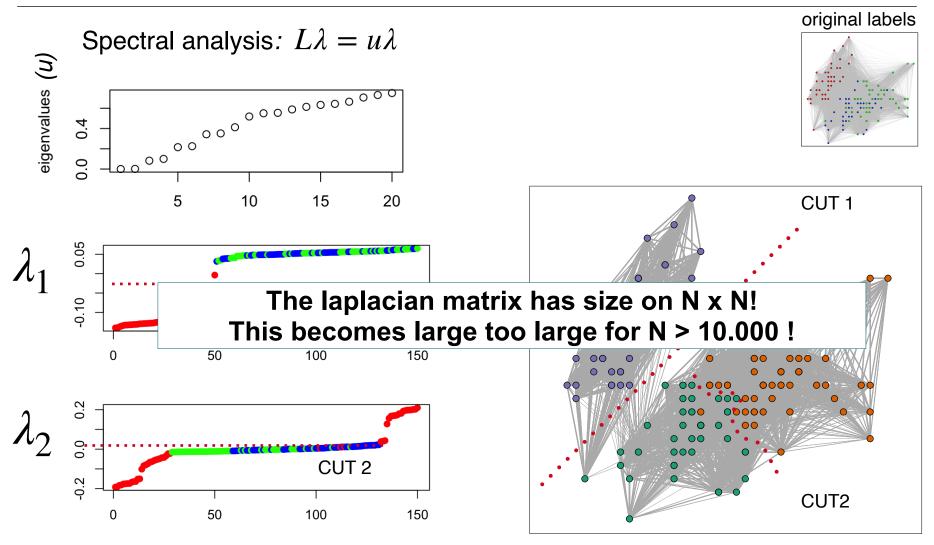




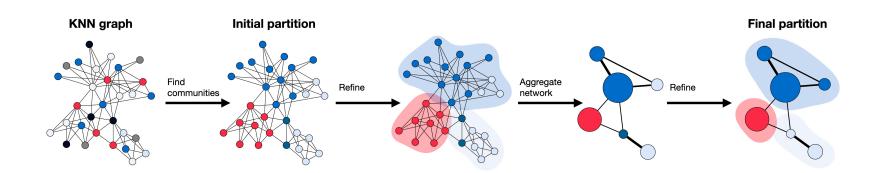








Single cell Clustering / Louvain & Leiden algorithm



Optimize cluster modularity

$$\mathcal{H} = \sum_{c} [e_{c} - \gamma(\frac{n_{c}}{2})],$$

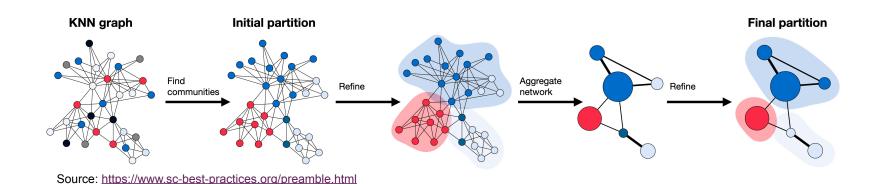
where n_c is the size of cluster and e_c is the number of expected edges

Source: https://www.sc-best-practices.org/preamble.html

- A) Start with a random partition
- B) Cluster objects improving H
- C) Create a meta-graph level:
 - one meta-node for each cluster
- D) Move objects improving *H*



Single cell Clustering / Louvain & Leiden algorithm



Optimize

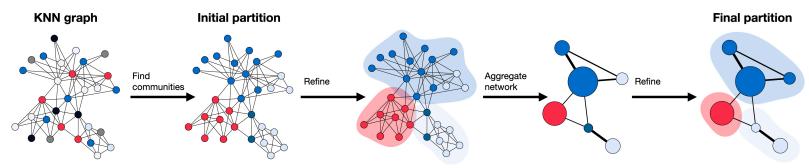
Meta-nodes and sparse graphs (knn) allows Leiden/Louvain to cope with millions of objects!

$$\mathcal{H} = \sum_{c} [e_c - \gamma(\frac{n_c}{2})],$$

where n_c is the size of cluster and e_c is the number of expected edges

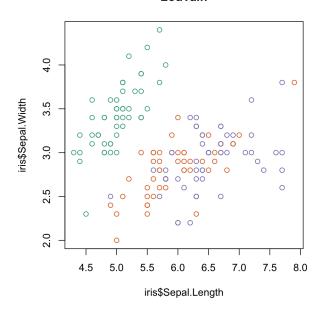
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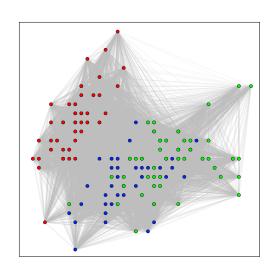
Single cell Clustering / Louvain & Leiden algorithm



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Louvain









Resume / Clustering Methods

- K-means, hierarchical clustering, spectral clustering
 - standard algorithms with standard performance on simple clustering problems
- Clustering of single cell algorithms
 - Leiden and louvain clustering
 - Robust and scale well to large data sets on sparse graphs (knn)
- Further issues:
 - Data dimensionality:
 - distances do not work well on high dimension
 - visualisation is easier in low level space
 - Validation:
 - How many clusters is present in the data?
 - Which is the best method?

More details on clustering

- Hastie, Tibshirani and Friedman, The Elements of Statistical Learning, Chapter 14
- Video lecture: https://www.youtube.com/watch?v=Qa6k7Rlwltg





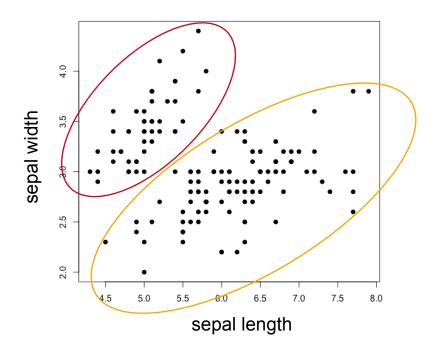
Clustering & Dimension reduction



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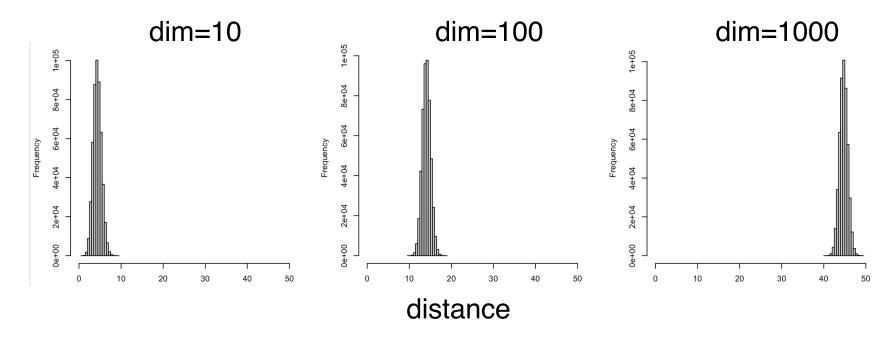


Dimension Reduction

Distances lose meaning at high dimensional space (curse of dimensionality)

$$\frac{D_{\max} - D_{\min}}{D_{\min}} \to 0.$$

Example: distance between points sampled from a normal distribution





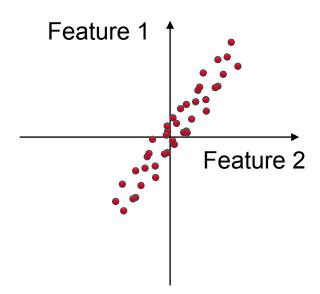
Dimension Reduction

- Distances lose meaning at high dimensional space (curse of dimensionality)
- Unspecific Filtering (without class labels):
 - Keep variables with highest variance (high variable genes)
 - Rationale: important features change values across groups
- Dimensionality Reduction by Transformation:
 - linear: principal component analysis (PCA)
 - Non-linear / manifold learning: t-SNE & UMAP (for visualisation)



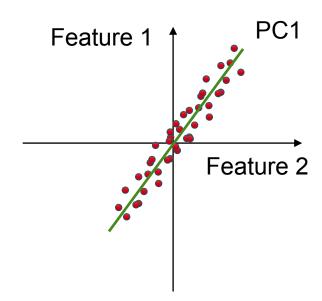
 For a data X, find linear combination of features (w) capturing most of data variance

$$\mathbf{w}_{(1)} = \underset{\|\mathbf{w}\|=1}{\text{arg max}} \{ \|\mathbf{X}\mathbf{w}\|^2 \}$$



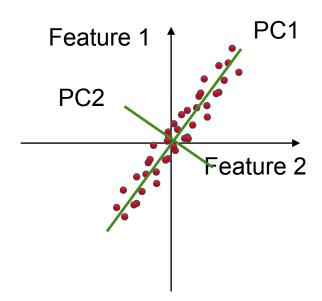
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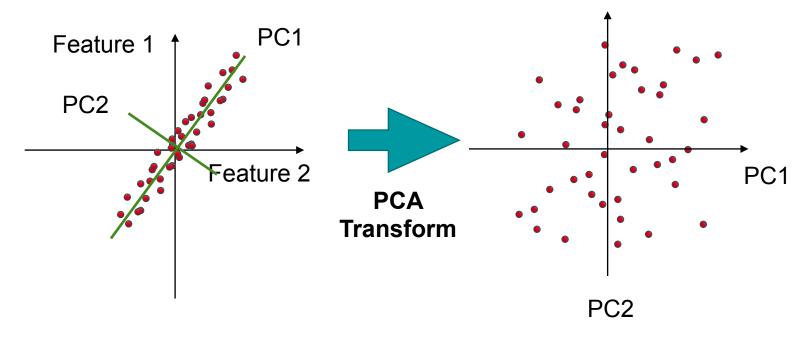
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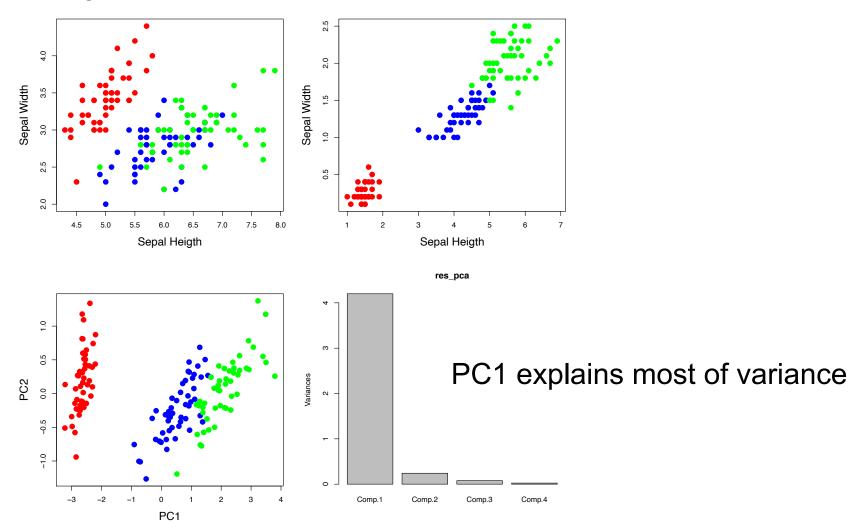
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PCA - Iris

Original iris data had 4 variables

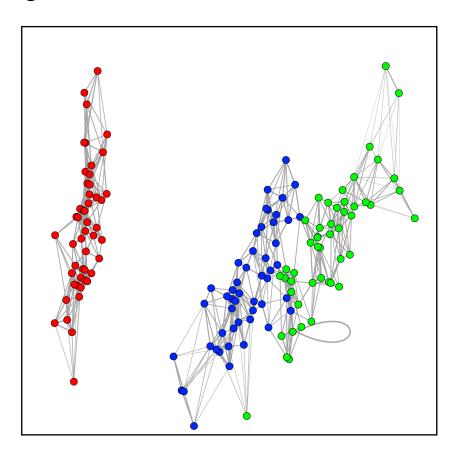




Clustering on PCA space

- For single cell data it is usually cluster in PCA space
 - · This is crucial for high-dimensional data!

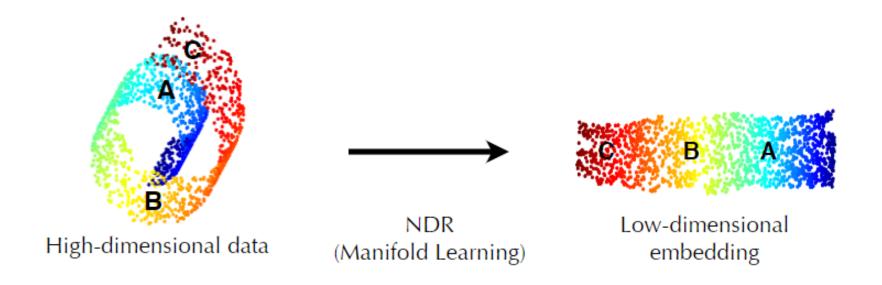
KNN graph of IRIS in PCA space





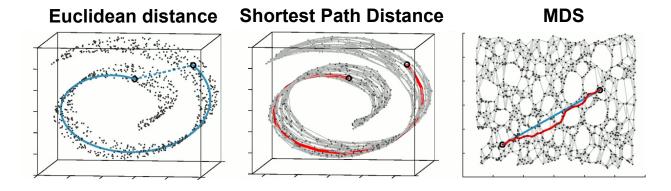
Non-linear / Manifold methods

Data might be distributed at particular regions of a high dimensional space



Non-linear /Isomap

Explore topological distance on nearest neighbour graph



Isomap algorithm:

- (1) create a knn graph
- (2) estimate shortest path between nodes (Dijkstra's algorithm)
- (3) use multidimensional scaling (MDS) on shortest paths

MDS algorithm:

find vectors
$$y_1, \dots, y_n \in Y^N$$
 such that $\sum_{i,j} (|y_i - y_j| - d_{ij})^2$

where d_{ij} is the similarity between nodes and N = 2



Non-linear methods

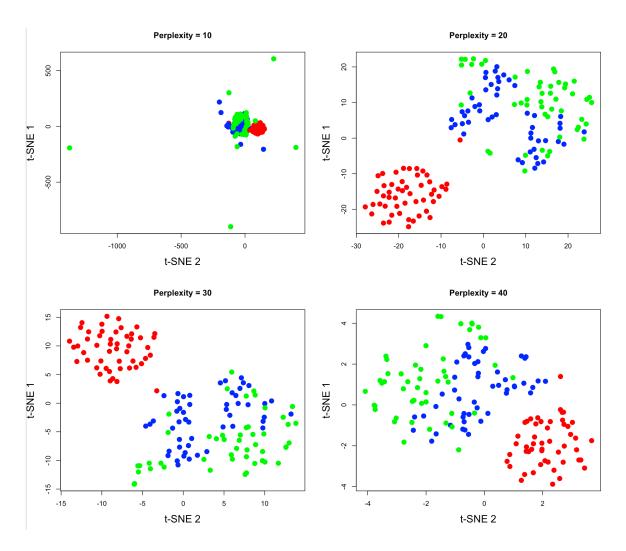
- Variants of Isomap (t-SNE or UMAP) are currently used
- t-SNE for a given kernel (similarity) D learn a N dimensional map Y

$$KL(D | Q) = \sum d_{ij}log(\frac{d_{ij}}{q_{ij}})$$
 where $q_{ij} = \frac{|y_i - y_j|^2}{\sum_k \sum_l |y_k - y_l|^2}$

KL - Kullback-Leibler divergence



t-distributed stochastic neighbour



- Sensitive to distinct starts and parametrisation
 - Perplexity ~
 neighbourhood (k)
 size
- t-SNE focus on preserving close neighbourhood

Non-linear methods

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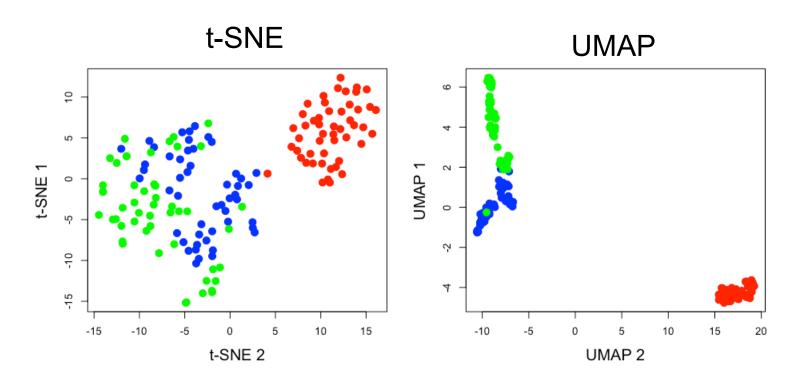
UMAP - dimension reduction based on Fuzzy Simplicial Sets

$$C((A, \mu), (A, \nu)) = \sum_{a \in A} \mu(a) \log \left(\frac{\mu(a)}{\nu(a)}\right) + (1 - \mu(a)) \log \left(\frac{1 - \mu(a)}{1 - \nu(a)}\right)$$

uses negative samples (non-neighboors) increasing repulsion between non-neighboors!

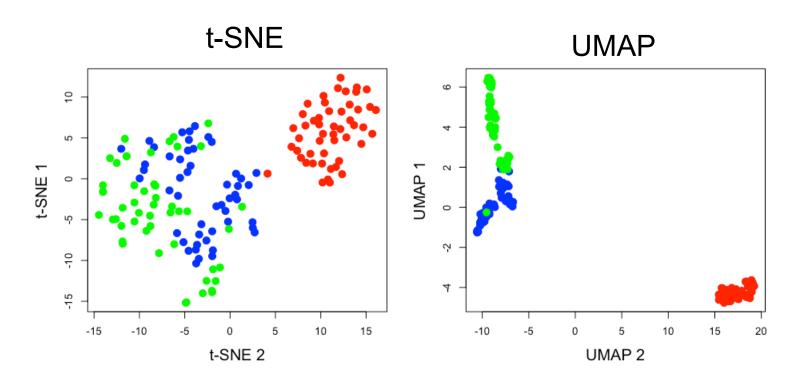


Manifold learning and IRIS



- Nice low dimensional visualisation of the data
- Caution: These methods fail capturing global structures (distance between clusters!)

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Resume / Dimension Reduction

- PCA analysis is a wide spread technique to reduce dimension!
 - Can only capture linear relationships
- Manifold methods
 - Nice low dimensional representation of data
 - Require parametrisation and lose global distance information

Complete course on manifolds/dimension reduction:

https://www.youtube.com/watch?v=evGm6lJKrDl

https://www.youtube.com/watch?v=CsUqmug7ZMc



Calendar

- 17.04.2023 Introduction to Bioinformatics and Single Cell Sequencing Analysis
- 24.05.2023 Single Cell Sequencing Analysis (cont.) & Practice
- 8.05.2023 Introduction to HPC clusters and GPU / Project Proposal
- 15.05.2023 3.7.2023 Project development
- 10.07.2023 Project Presentation

Communication/discord channel: https://discord.gg/hmGxznNpZH .



Thank you!



Cluster Validation

- How to evaluate clustering results? Which is the best method? How many clusters?
- Internal/relative validation:
 - Measure of cluster coherence:
 - Distance within a cluster -> small (compactness)
 - Distance between clusters -> high (separation)
 - Stability measures:
 - Cluster data in part of the data and compare results
- External validation:
 - Compare clusters with class labels (iris data)
 - Not possible in real word problems!



Silhouette - Internal Index

The silhouette for a given object *i* is defined as:

$$s(i) = \frac{b(i) - a(i)}{max(a(i), b(i))}$$

where

a(i) -mean distance of i to objects on same cluster (compactness) d(i,k) - mean distance of i to objects of cluster k (not own) $b(i) = min_k (d(i,k))$ (separation)

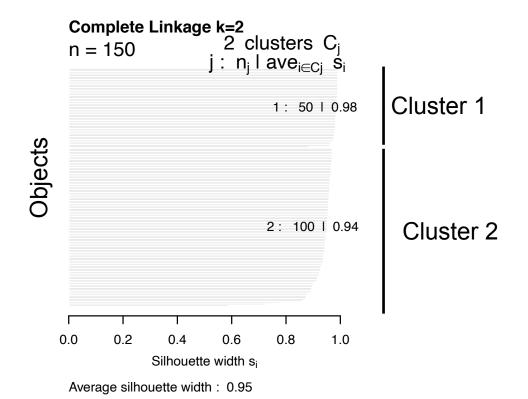
Average of s(i) -> quality of all results or clusters

Value of 1 indicate perfect solutions!



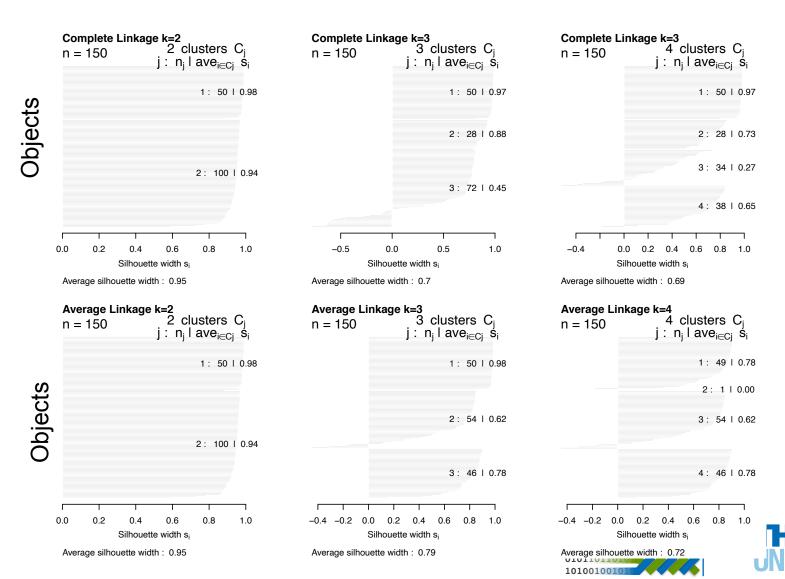
Silhouette - Internal Index / Iris

silhouette values for hierarchical clustering with Pearson



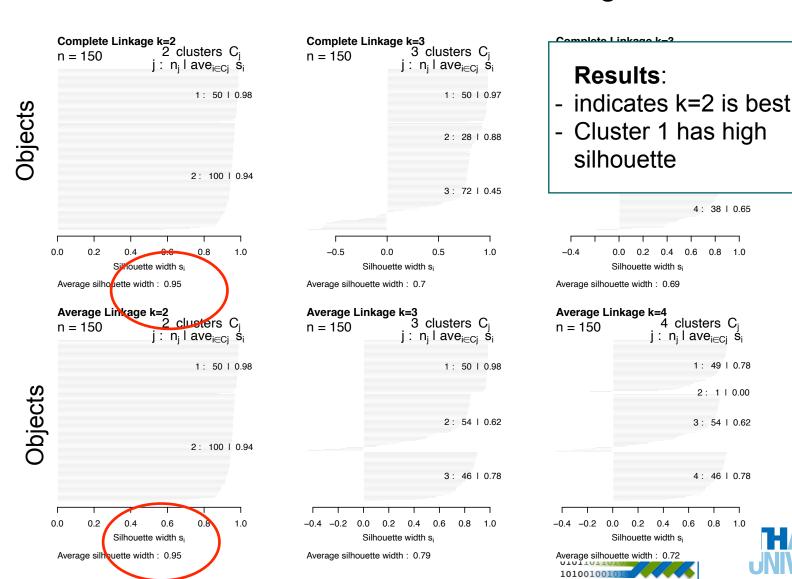
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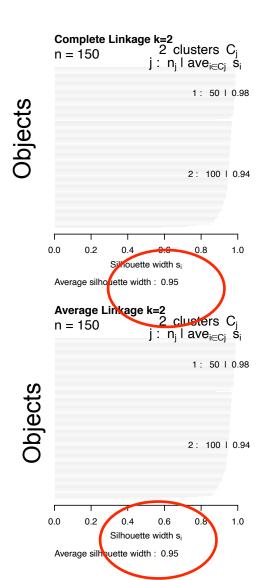
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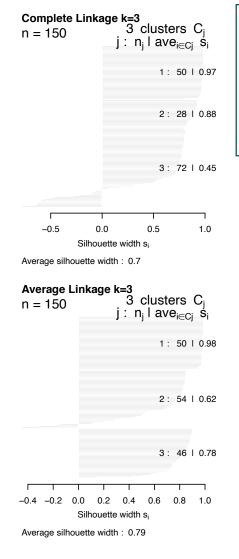
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Silhouette - Internal Index / Iris

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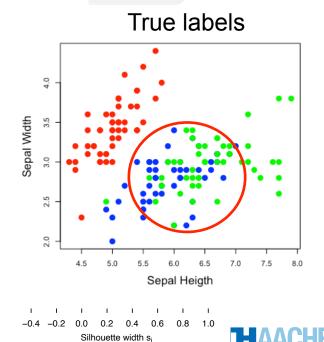


Results:

- indicates k=2 is best
- Cluster 1 has high silhouette

Average silhouette width: 0.72

1010010010



Gap statistic - Internal Index

For a given solution with *K clusters*

$$W_K = \sum_{k=1}^K \sum_{y_i = k} \sum_{y_j = k} ||x_i - x_j||^2$$

 W_K - measures cluster compactness

 W_K - tends to 0 for increasing K

The Gap Statistic consider clustering of random data W*

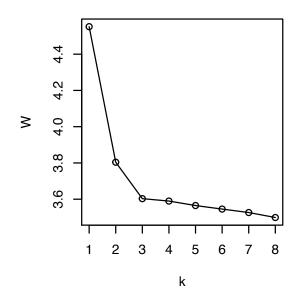
$$GAP(k) = E_r[logW_K^*] - logW_K$$

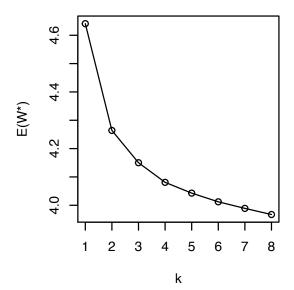
where *W** estimated from clustering random points at the same data space of *X*

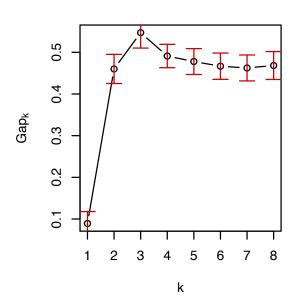


Gap statistic - Iris

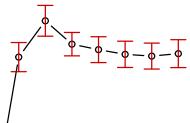
GAP statistics for Iris / Average Linkage with Pearson

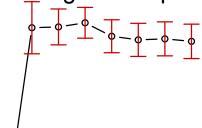


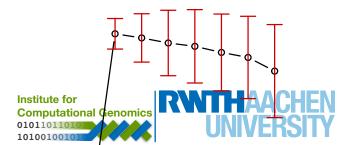




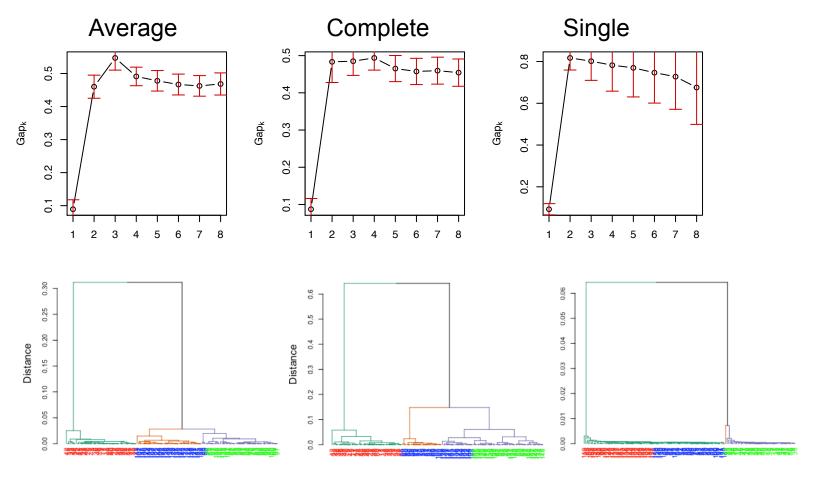
3 clusters has highest Gap !!!







GAP statistics for distinct linkage methods



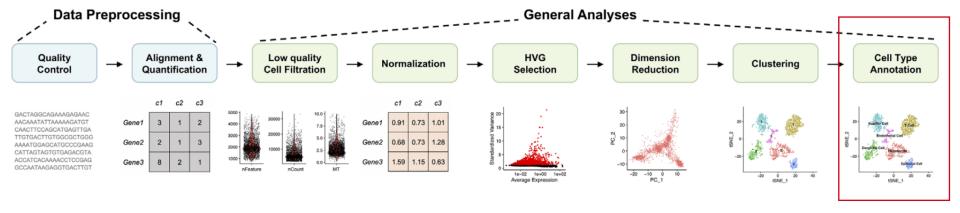


Resume / Validation

- Help detection of number of clusters / real clusters
 - Do not work perfectly!
- GAP statistics is widely used
 - Requires r data randomisations
 - high computational costs
 - random datasets uniformly distributed (unreal assumption)
- Expert interpretation is important!

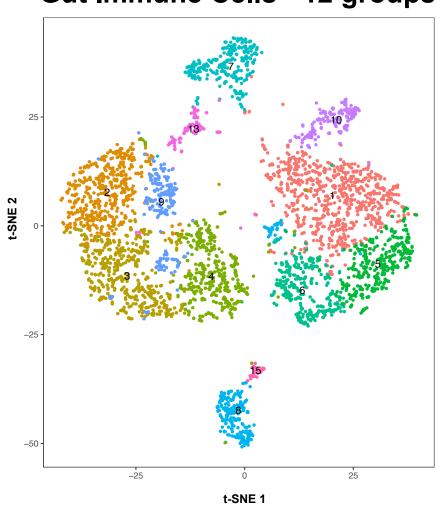


Basics Bioinformatics - single cell RNA-seq



Basics Bioinformatics - Clustering

Gut Immune Cells - 12 groups



Clustering - identify cells with similar expression patterns

- based on PCA (20 dimension)

How to identify cell types?



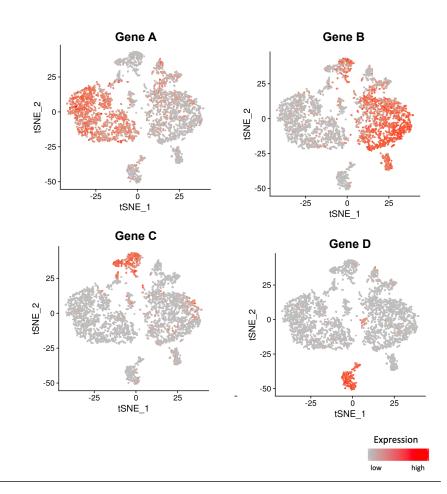
Cell Identity with an Expert

Gut Immune Cells - 12 groups

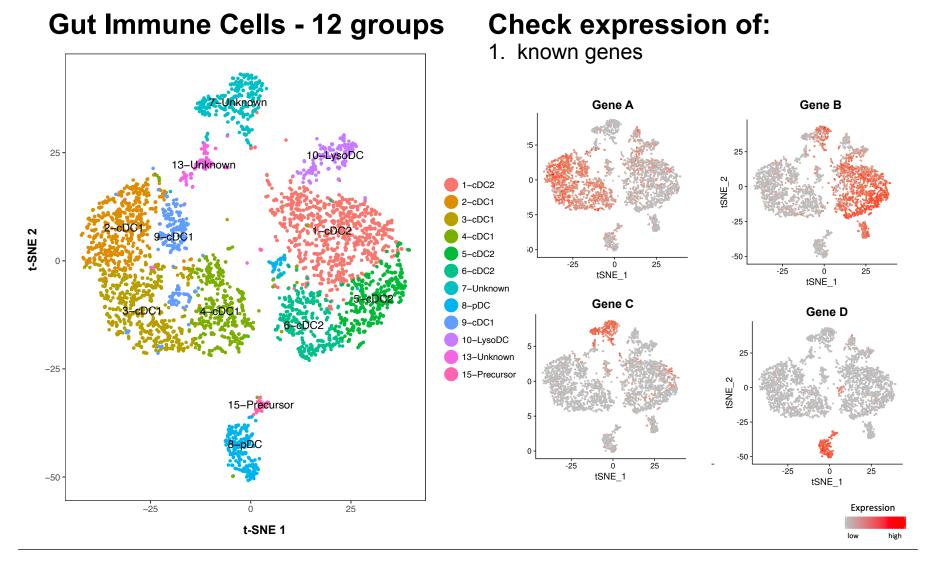
25 t-SNE 2 -25 -50 -25 t-SNE 1

Check expression of:

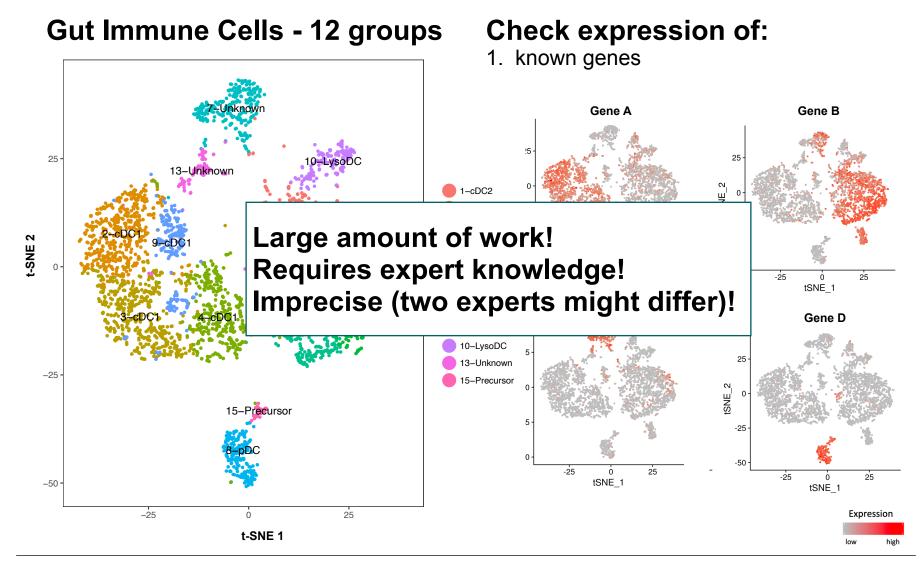
1. known genes



Cell Identity with an Expert



Cell Identity with an Expert



Resume / Single cell clustering

- Finding groups of single cells require complex pipeline:
 - Cell filtering
 - Normalisation
 - Artefact removal
 - Dimension reduction
 - Integration
 - Clustering
 - Cell annotation / visualisation
- Open points:
 - How to deal with large data sets (millions of cells)?
 - How to detect cells of rare populations?



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